



Coupled Oscillators and Hysteresis in Sparse Networks



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Acknowledgements: We thank Ross Parker and Alejandro Aceves for their assistance. Work funded under NSF-RTG grant #1840260.

Background

- Sets of oscillators tend to synchronize when coupled in some manner.

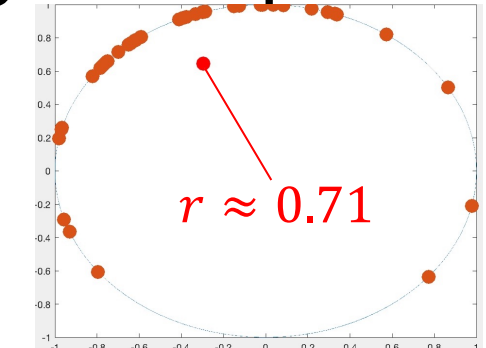
- Oscillators modeled by initial frequency ω_i and current phase $\theta_i(t)$.

Kuramoto Model:

- All N oscillators coupled to all others with strength K .
- Change of phase θ_i depends on difference in current phase of all other oscillators:

$$\frac{d\theta_i}{dt} = \omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_i - \theta_j)$$

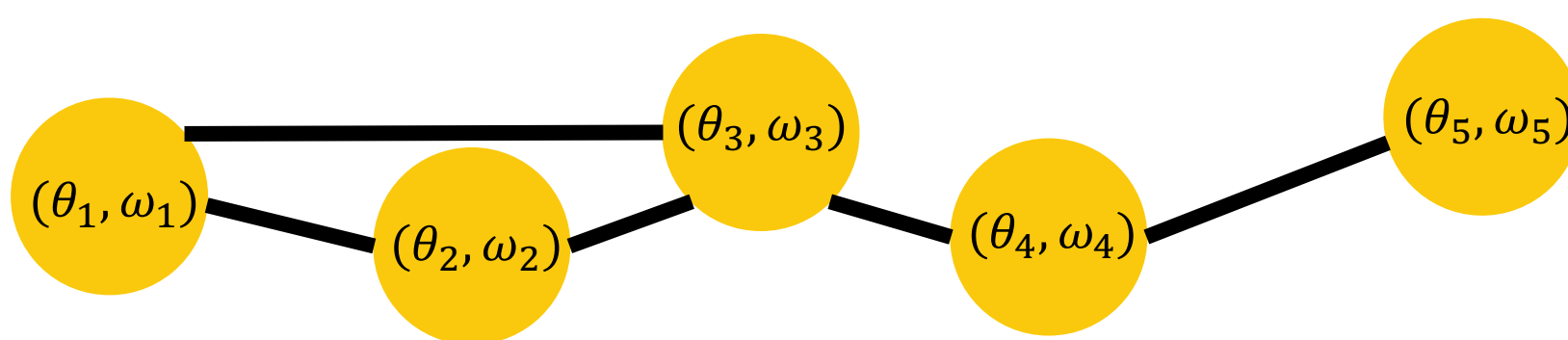
- Synchrony often measured using order parameter r :

$$r(t) = \left| \frac{1}{N} \sum_{j=1}^N e^{i\theta_j(t)} \right|$$


Kuramoto Model on Graphs

- Arbitrary couplings defined through graph $G = (V, E)$.
 - V is the set of oscillators.
 - E is the set of couplings between oscillators.
- Change of phase θ_i depends on phase of neighbors:

$$\frac{d\theta_i}{dt} = \omega_i + \sum_{j=1}^N K a_{ij} \sin(\theta_i - \theta_j)$$



Implementation

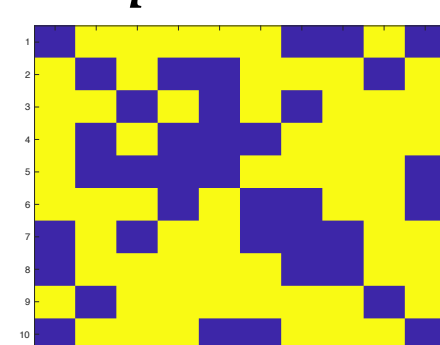
Order parameter r only for connected graphs

- We only consider networks with adjacency matrix A such that:

$$A(p) = [a_{i,j}] \text{ s.t. } p = \frac{1}{N^2} \sum_{i,j=1}^N a_{i,j}$$

ex: $N = 50$, $p = 0.7$

$$a_{i,i+1} = a_{i+1,i} = 1, a_{i,i} = 0 \quad \forall i$$



- Level of graph connectivity varied by p .

Initial conditions for solving IVP:

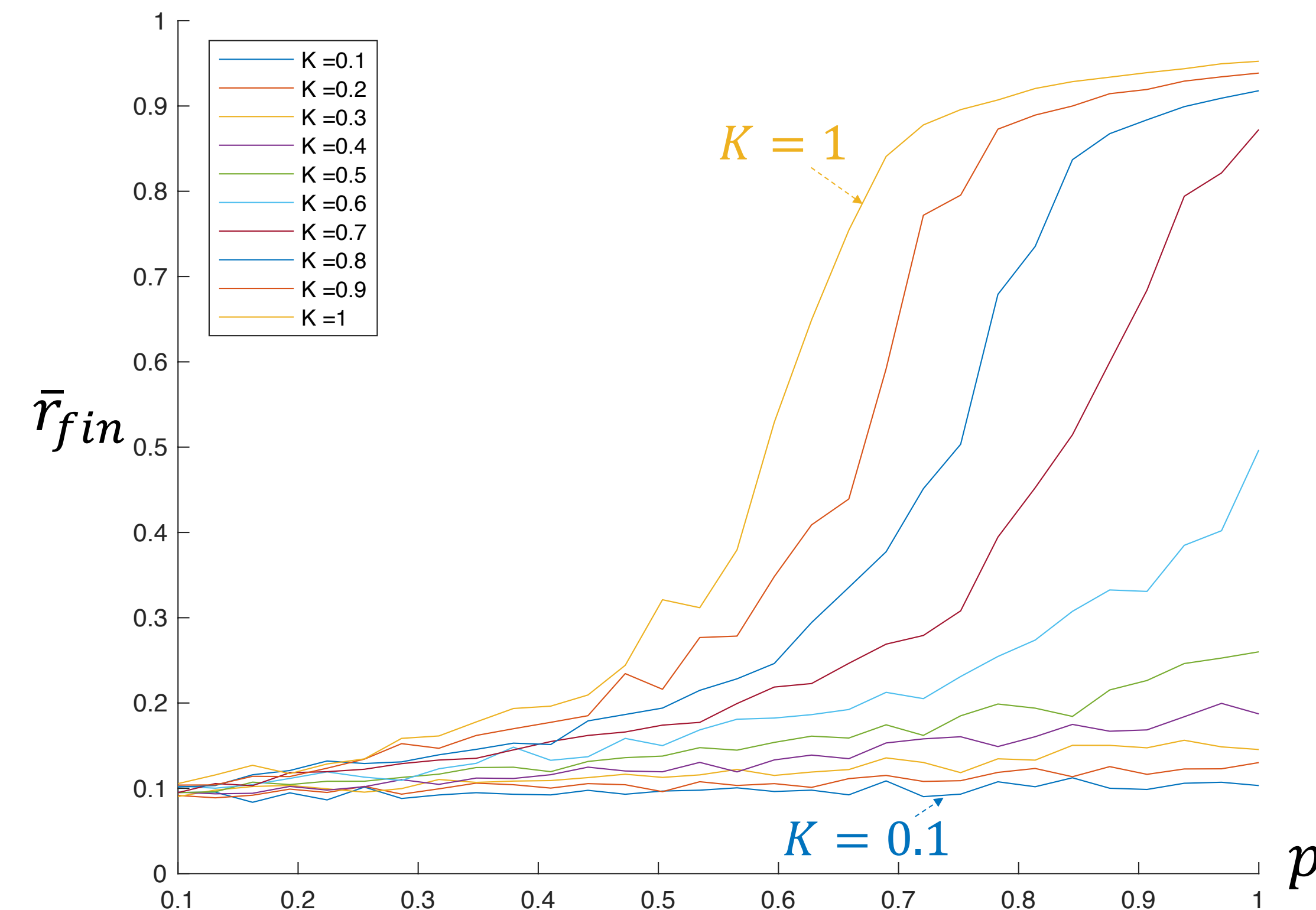
- Normally distributed frequencies $\{\omega_i\} \stackrel{i.i.d}{\sim} \mathcal{N}(0, 0.1)$
- Uniformly distributed initial phase $\{\theta_i(0)\} \stackrel{i.i.d}{\sim} \text{Unif}(0, 2\pi)$

- Runge - Kutta 4th order ODE solver, $dt = 0.1$

Results: Static K and p

- Order parameter at 1000 steps recorded for each (K, p) .

- 500 Oscillators, Results averaged over 10 trials



Conclusions

- For static coupling K and connectivity p :
 - Sigmoidal relationship between synchronization ability and network connectivity p for each coupling K .
- For time varying coupling $K(t)$ and static connectivity p :
 - Hysteresis increases or decreases with p depending on the choice of coupling function $K(t)$.
 - Connectivity is not a hysteresis operator on r depending on K and initial state: heavily rate dependent.

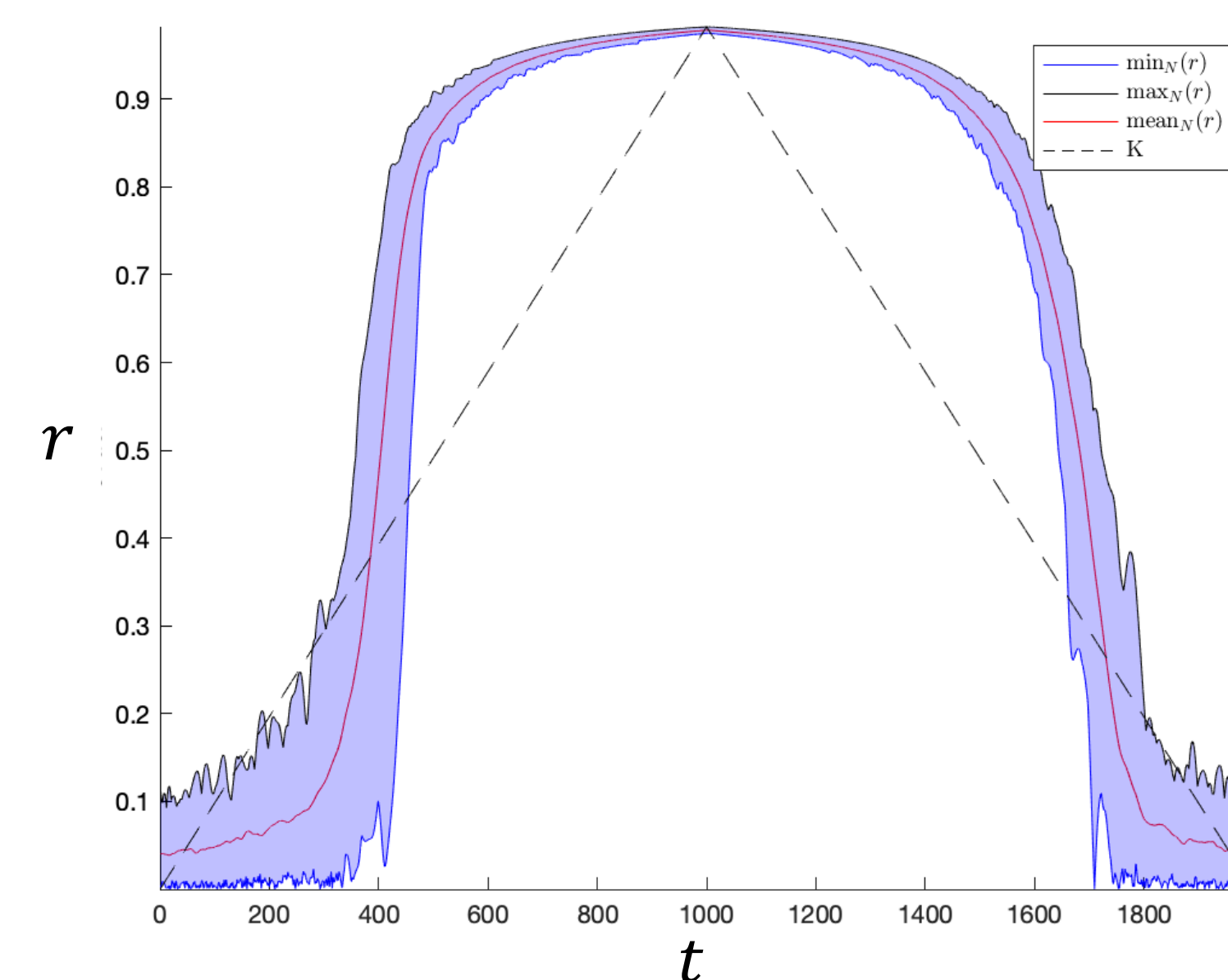
Future work

- Why does hysteresis occur?
- What determines the size of this hysteresis effect?
- Why does hysteresis grow/shrink with connectivity?
- What property of $K(t)$ determines the direction?
- Verify results for other constructions of connected graphs.

Results: Time Varying $K(t)$, Static p

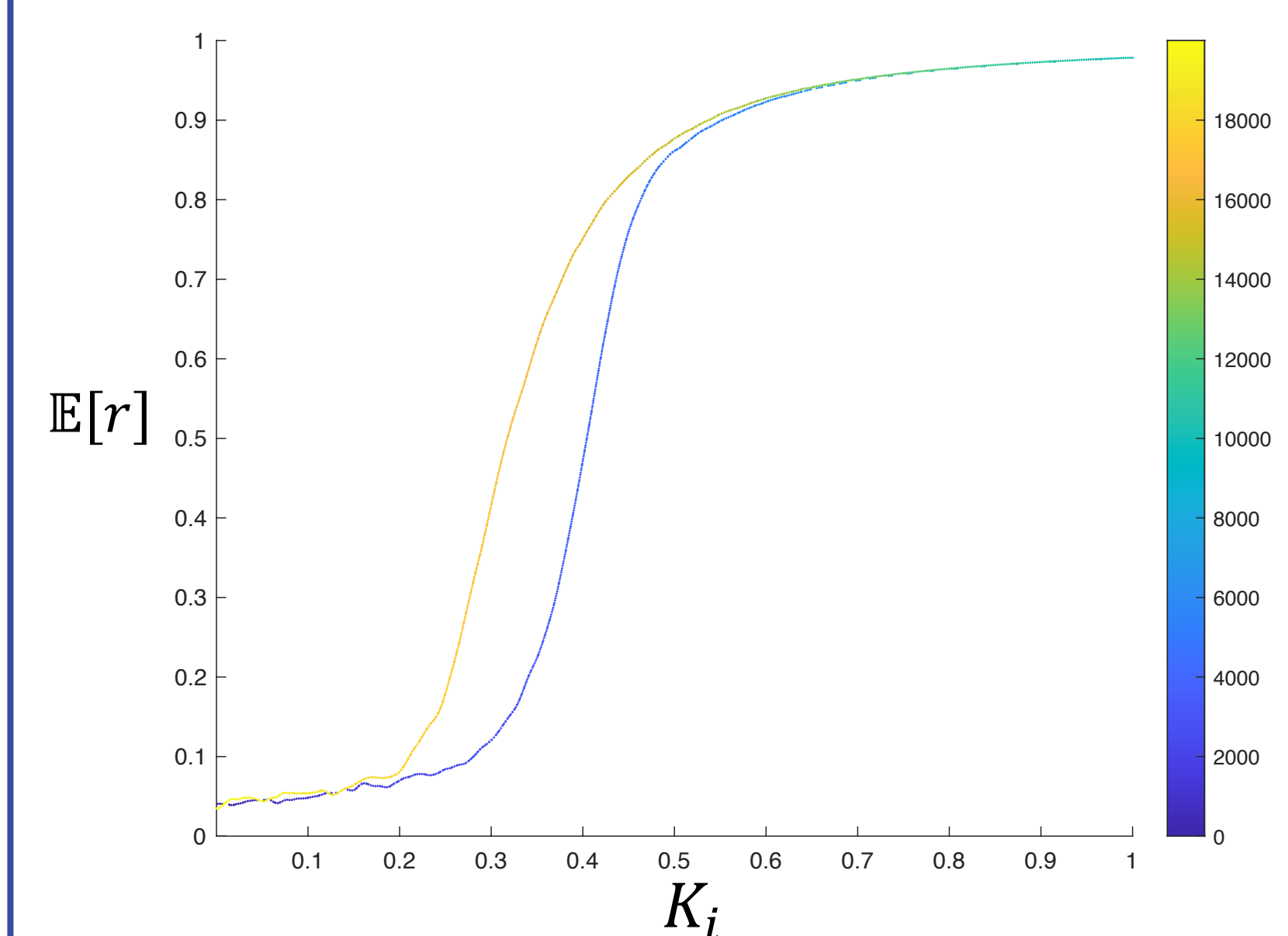
- Synchrony $r(t)$ measured over time while the coupling $K_i(t)$ is varied.

- Shown: $r(t)$ range over 100 trials for 500 oscillators at $p = 0.50$ with K_1 - a triangular function.

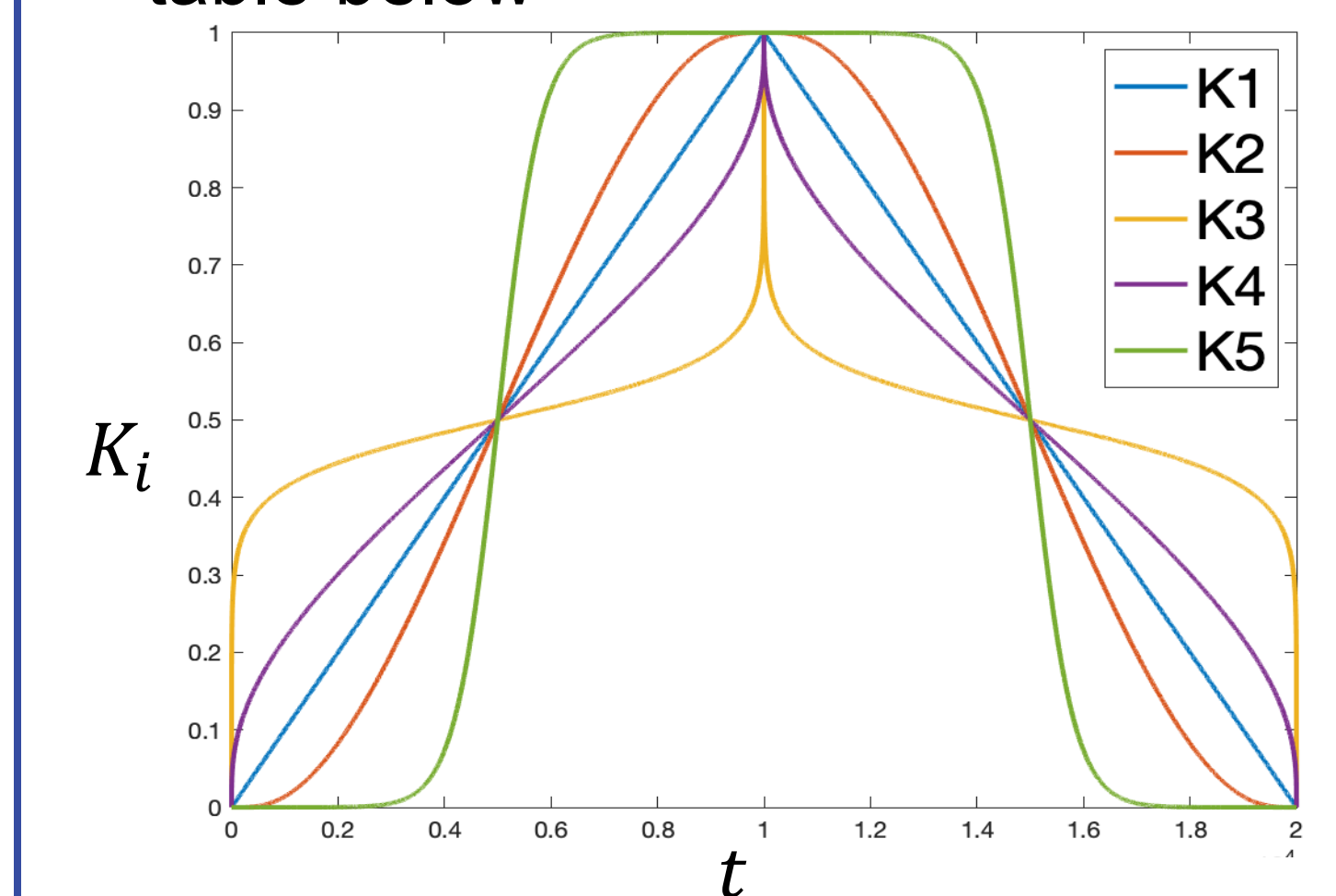


- Hysteresis effect seen as $\mathbb{E}[r(t)]$ is plotted as a function of $K_i(t)$. [\mathbb{E} is over 100 trials]

- Shown: $\mathbb{E}[r(t)](K)$ 500 oscillators at $p = 0.50$ with triangular K_1 .



- Shown: K_i referenced in hysteresis table below



p :	0.25	0.50	0.75	1.00
K_1	0.033	0.032	0.030	0.030
K_2	0.043	0.045	0.041	0.039
K_3	0.047	0.151	0.242	0.262
K_4	0.028	0.029	0.035	0.045
K_5	0.128	0.139	0.116	0.092

Highlighted: highest (red) in row. Values normalized by number of steps T .

- Hysteresis effect for each (p, K_i) quantified by numerically finding the area between the two curves. K_i given by figure above table. 50 Oscillators with $\mathbb{E}[r]$ on 100 trials.

- All K_i bijective and monotonic increasing/decreasing on $(0, \frac{T}{2}) / (\frac{T}{2}, T)$ respectively, with boundary values $\|K_i\| = \frac{T}{2}$, $K_i(0) = K_i(T) = 0$, $K_i(\frac{T}{2}) = 1$.